

WRF-EDAS for assimilation and downscaling of the GPM satellite precipitation information



Milija Zupanski¹, Sara Q. Zhang², and Samson H. Cheung³

¹Colorado State University, Fort Collins, CO

²NASA Goddard Space Flight Center, Greenbelt, MD

³University of California, Davis, CA

Corresponding author E-mail: Milija.Zupanski@colostate.edu

Goals

- Develop an operation-ready system for downscaling and assimilating GPM precipitation-affected satellite radiances for improvement of rainfall estimates at high resolution suitable for hydrological modeling and prediction
- Assimilate conventional and satellite data to produce observation-constrained high-resolution precipitation analyses and short term forecasts, with uncertainties estimated from ensemble forecasts
- The following state-of-the art components are incorporated:
 - ✦ NASA Unified Weather Research and Forecasting (NU-WRF) model with NASA microphysics
 - ✦ NCEP Gridpoint Statistical Interpolation (GSI) forward observation operators for conventional and cloud cleared satellite observations,
 - ✦ Goddard SDSU with Goddard all-sky Radiative Transfer Model as forward operator for precipitation sensitive satellite radiances
 - ✦ CSU Maximum Likelihood Ensemble Filter (MLEF) data assimilation method as framework for addressing non-linear and discontinuous data assimilation problems (Zupanski 2005; Zupanski et al. 2008)
- Explore applications of the precipitation analyses and forecasts for improving hydrological forecasts
- Address the following problems: (1) insufficient rank of forecast error covariance in ensemble data assimilation, and (2) Radiance bias correction for precipitation-affected satellite radiances
- Algorithmic development of NU-WRF-EDAS as an operation-ready system

Hybrid forecast error covariance

- ✦ Ensemble error covariance is important since it is flow-dependent and describes complex cross-variable correlations.
- ✦ However, it has insufficient number of degrees of freedom, impacting the ability to assimilate all observations
- ✦ Include static (time-independent, variational) error covariance
- ✦ Create hybrid dynamic-static (i.e. ensemble-variational) error covariance

$$P_f^{1/2} = \begin{pmatrix} \alpha P_{dyn}^{1/2} & (1-\alpha)P_{stat}^{1/2} \end{pmatrix} \quad P_{stat}^{1/2} = P_{var}^{1/2} Q \quad \alpha = 0.7$$

Addressing radiance bias correction

- ✦ Precipitation-sensitive microwave radiances are particularly susceptible to approximations and assumptions on physical properties of precipitation in radiative transfer calculations and model cloud physics schemes
- ✦ Radiance bias correction using parameter estimation with DPR observations (Zhang et al. 2014)

$$s_{opt} = \arg \min_s |DFR_0 - DFR(s)|^2 \quad DFR = \frac{Z_{ku}}{Z_{ka}}$$

Assimilation of GMI all-sky radiance observations (May 15, 2014)

- ✦ Precipitation events over SE United States (IPHEX - May 1 – June 15, 2014)
- ✦ Assimilation of GMI all-sky satellite radiance at 89, 166, and 183+/-7 GHz over land surface
- ✦ Radiance bias correction using DPR reflectivity observations and parameter estimation
- ✦ NU-WRF at 9 km / 3km resolution, 31 vertical layers
- ✦ Control variables include dynamic and cloud variables: perturbation surface pressure, perturbation temperature, perturbation height, winds, specific humidity, cloud water, cloud rain, cloud ice, cloud snow, and graupel.
- ✦ 32 ensemble members
- ✦ 3 hour assimilation interval

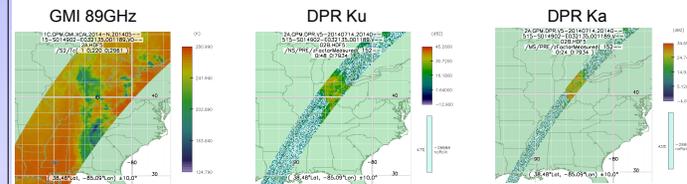


Figure 1. GPM observations on 15 May 2014 at 0000 UTC: all-sky GMI radiances, Ku and Ka DPR reflectivities. The DPR observations are used to estimate bias correction for GMI assimilation.

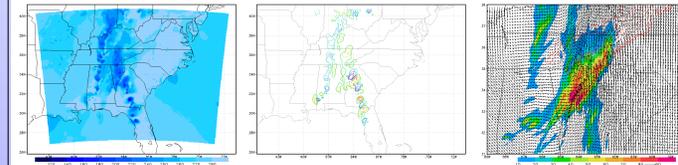


Figure 2. Assimilation of precipitation-affected GMI radiance observations: (a) simulated GMI radiance (left panel) valid 15 May 2014 at 0000 UTC, hydrometeor analysis increments (middle panel) valid 15 May 2014 at 0000 UTC, and verified using the accumulated 6-hour forecast (right panel) valid 15 May 2014 at 0600 UTC.

- ✦ Positive impact of GMI radiance assimilation on precipitation and near-surface wind.
- ✦ The accumulated precipitation forecast (0-6 h) is improved by 23% in RMSE verified using ground validation observations.

Additional, more detailed results with GMI all-sky radiance assimilation are presented on the poster #242 by Zhang et al.: *"Dynamical Downscaling GPM data and MERRA2 global reanalysis using NU-WRF EnDA System: a case study of 2014 Thanksgiving Winter Storm"*

Preparation for an operation-ready NU-WRF EDAS

- ✦ **Speed:** Computational efficiency is required for real-time processing.
- ✦ **Flexibility:** Algorithm structure that facilitates assimilation of new observation types, such as those from the GPM Ground Validation (GV) network
- ✦ **Reliability:** Computational stability of the system and steady performance.

Algorithmic development of NU-WRF EDAS

- ✦ Unified data assimilation algorithm as a single program
- ✦ Separate shell scripts/executables for numerical model (e.g., NU-WRF) and for observations (e.g., NOAA GSI, NASA G-SDSU)
- ✦ Modular approach: Each component of data assimilation is a separate module: main data assimilation driver, minimization, error covariance localization, ...
- ✦ Numerical model and observation operator included through a modular interfaces. Only the interface module contains variables relevant to the particular model or observation operator; they are converted into the data assimilation variables.
- ✦ User-friendly design of input namelist parameters
- ✦ MPI-based system for parallel processing

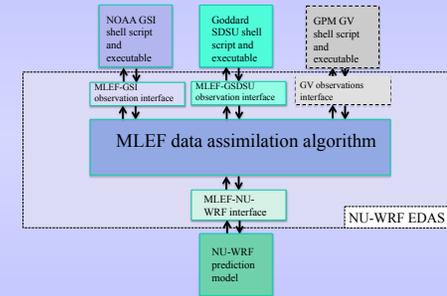


Figure 3. Flow-chart of NU-WRF EDAS. The current NU-WRF EDAS encompasses the MLEF data assimilation algorithm and interfaces with NU-WRF model and observations (GSI, GSDSU) observations. In the future we plan to add GPM Ground Validation (GV) observations.

Conclusions

- NU-WRF-EDAS successfully applied to assimilation of GMI all-sky radiances
- Other capabilities include assimilation of NOAA operational observations (GSI), radiance bias correction, and hybrid dynamic-static error covariance
- NU-WRF EDAS is a modular MPI algorithm

Future Work

- ✦ Upgrade system to assimilate GPM Ground Validation (GV) observations
- ✦ Further improve system's efficiency

References:

Chambon, P., S. Q. Zhang, A. Y. Hou, M. Zupanski, and S. Cheung, 2014: Assessing the impact of pre-GPM microwave precipitation observations in the Goddard WRF ensemble data assimilation system. *Q. J. Roy. Meteorol. Soc.*, 140, 1219-1235

Zhang, S. Q., M. Zupanski, A. Y. Hou, X. Lin, and S. Cheung, 2013: Assimilation of precipitation affected radiances in a cloud-resolving WRF ensemble data assimilation system. *Mon. Wea. Rev.*, 141, 754-772.

Zhang, S. Q., M. Zupanski, S. Cheung, and P. Chambon, 2014: Assimilation of GPM observations in NASA Unified WRF EDAS. *AGU Fall Meeting*, December 15-19, 2014, San Francisco, CA.

Zupanski, D., S. Q. Zhang, M. Zupanski, A. Y. Hou, and S. H. Cheung, 2011: A prototype WRF-based ensemble data assimilation system for dynamically downscaling satellite precipitation observations. *J. Hydrometeorology*, 12, 118-134.

Zupanski, M., 2005: Maximum Likelihood Ensemble Filter: Theoretical Aspects. *Mon. Wea. Rev.*, 133, 1710-1726.

Zupanski, M., I. M. Navon, and D. Zupanski 2008: The maximum likelihood ensemble filter as a non-differentiable minimization algorithm. *Q. J. Roy. Meteor. Soc.* 134, 1039-1050.

Acknowledgements:

Financial support was provided by the NASA GPM Program under contract No. NNX13AG96G. Computational resources were provided by Pleiades supercomputer at NASA's Ames Research Center.