

Towards Improving Self-Consistency Between GPM Constellation Passive MW Precipitation Retrievals

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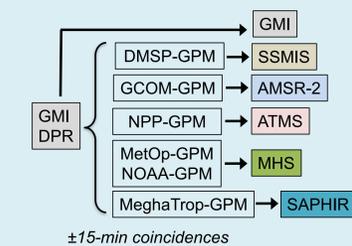
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With acknowledgements to members of the PMM Land Surface Working Group

Summary

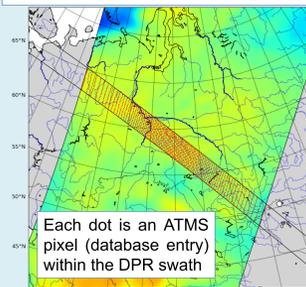
One of the key challenges for GPM is how to link the information from the single GPM core DPR across all passive MW sensors in the constellation, to produce a globally consistent precipitation product. With now 3.5 years of GPM data, there are abundant near-coincident (± 15 -minute) coincidences between GPM and each constellation radiometer. This affords an opportunity to examine the suitability of purely observational databases for building sensor-specific *a-priori* datasets appropriate for Bayesian-type precipitation estimation techniques.



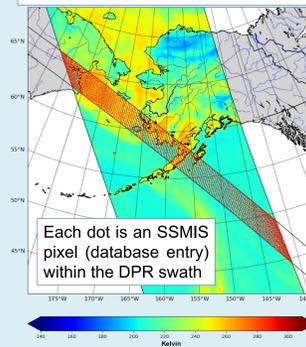
Observational Databases

Existing DPR Ku- and Ka-band uncorrected Z profiles and precipitation rate retrievals from ± 15 -min coincidences between GPM and each of the constellation radiometers are directly transferred into the databases. Four DPR-based retrievals are currently used: the NS- and MS-based estimates from the DPR-only and the CORRA combined (see **Nomenclature** below). This allows verification of not only conventional surface precipitation, but allows assessment of the vertical structure of the DPR profiles that were selected by the radiometer-only retrieval.

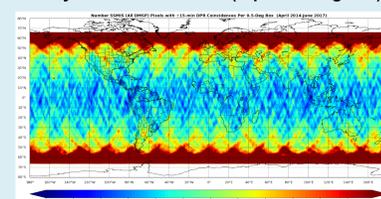
GPM-NPP 01/28/2017 Near 2122 UTC



GPM-F17 04/01/2014 Near 0337 UTC

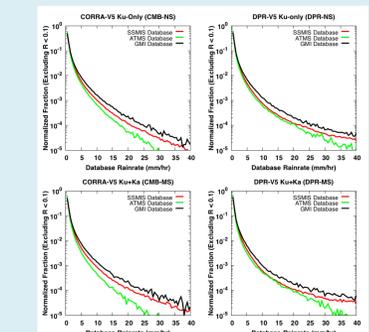


Density of SSMIS database (N per 0.5-deg box)



Database Sizes

N ATMS DB entries= 22M (04/2014-06/2017)
N SSMIS DB entries= 90M (04/2014-06/2017)
N GMI DB entries= 850M (09/2014-09/2015)
MHS, AMSR-2 in progress



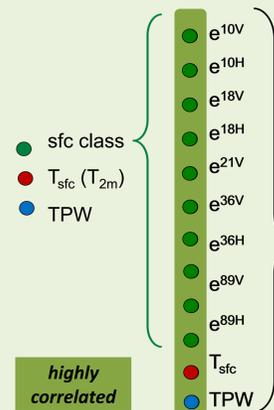
Normalized histograms of raining entries, for each of the four DPR-based algorithms (panels) and three sensor databases (colors)

Surface-Based Indexing and Weighting

Since the constellation MW radiometers routinely observe many more non-precipitating conditions than precipitating, the information content within the 3.5 years of non-precipitating GPM observations is examined to characterize the global MW surface emissivity variability, (regardless of surface type), and use this information to design an indexing structure to search *a-priori* data and weight candidate solutions.

Principle

Ideally, if one could obtain a reasonable estimate of the emissivity vector at the observation time, this formulation would better accommodate day-to-day (or shorter) changes in the surface emissivity properties.



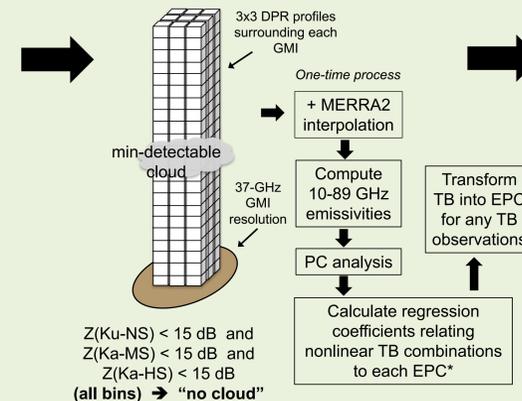
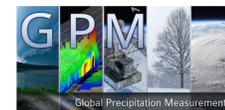
emissivity principal component analysis (EPC)

- EPC1
- EPC2
- EPC3
- EPC4

First four EPC explain the vast majority of the joint variability

Use these to index and search *a-priori* databases

The transformation of TB into **emissivity principal component (EPC) space**, (from which the emissivity state vector can be reconstructed) to probabilistically separate "no-cloud" and increasingly cloudy and precipitating scenes is described in (Turk et al. 2014; Turk et al., 2016*).

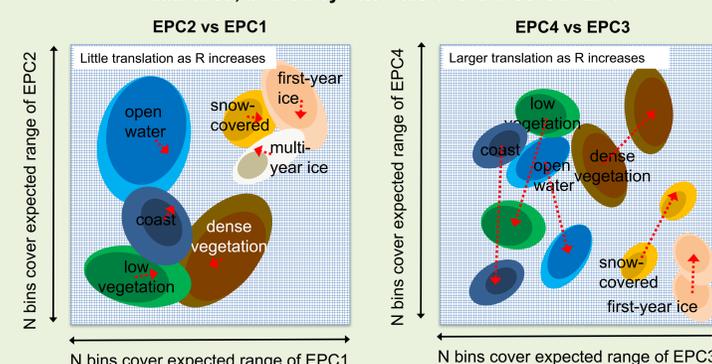


Z(Ku-NS) < 15 dB and Z(Ka-MS) < 15 dB and Z(Ka-HS) < 15 dB (all bins) → "no cloud"

The method appears to identify self-similar surface types directly from the TB observations, without requiring any knowledge of geographical location, surface or environmental/temperature conditions.

*Turk, F.J., Haddad, Z.S. & You, Y., 2016, Estimating Non-Raining Surface Parameters to Assist GPM Constellation Radiometer Precipitation Algorithms, *J. Atmos. Oceanic Technol.*, 33, 1333-1353.

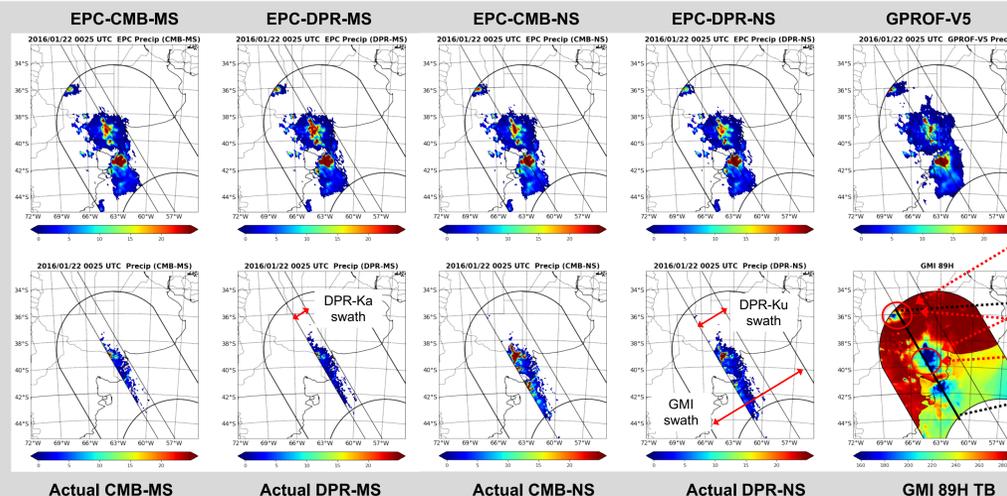
2-Dimension projection of an EPC-indexed database, binned by intervals of the first four EPC



The self-separation of the underlying surface types are mainly carried by the higher order terms (EPC1 and EPC2). The range (clusters) don't shift very much from their quiescent (no-precipitation) range as precipitation develops.

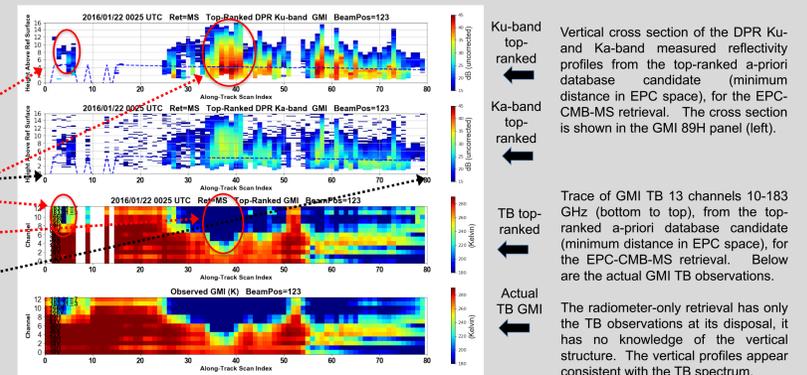
(not quantitative – for illustrative and conceptual purposes only)

As clouds and increasingly higher precipitation enters the radiometer field-of-view, the lower order terms (represented here by EPC3 and EPC4) display a more noticeable shift. This suggests the use of the EPC as a database indexing scheme, and also as a metric for searching and weighting Bayesian-based precipitation techniques.

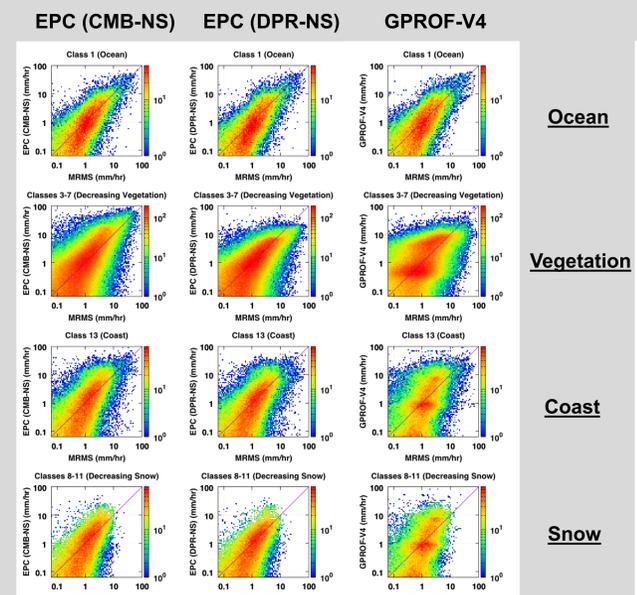


Example: Argentina 2016/01/22 0025 UTC

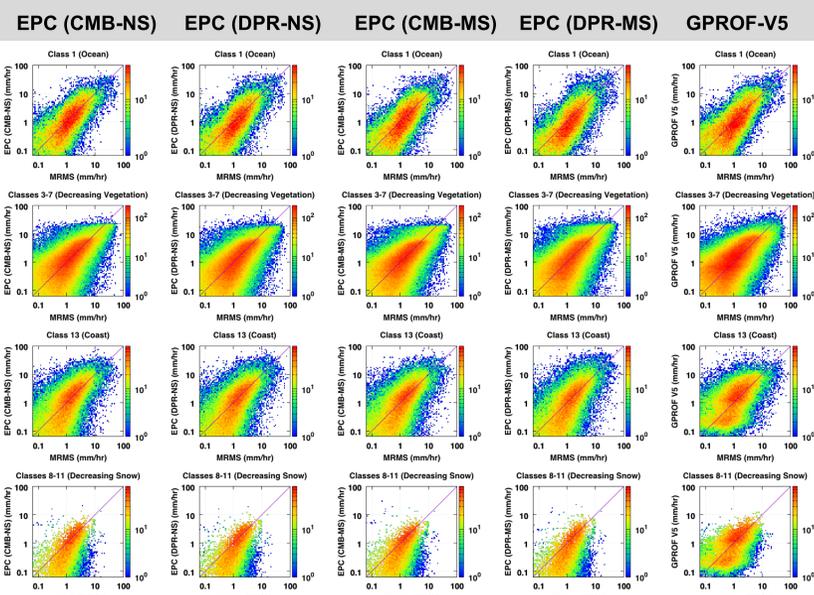
The figure to the left depicts the four EPC-based precipitation retrievals for this GPM overpass, where (top, left-to-right) the CMB-MS, DPR-MS, CMB-NS and DPR-NS precipitation rates are weighted by their distance in EPC space, from the observations. Beneath each are the corresponding actual precipitation rates from these same four algorithms.



EPC-Based Retrieval Overall Performance (Relative to GMI-Matched MRMS) Version 4 Datasets (seven months between Nov 2015 and Sep 2016)



EPC-Based Retrieval Overall Performance (Relative to GMI-Matched MRMS) Version 5 Datasets (same seven months between Nov 2015 and Sep 2016)



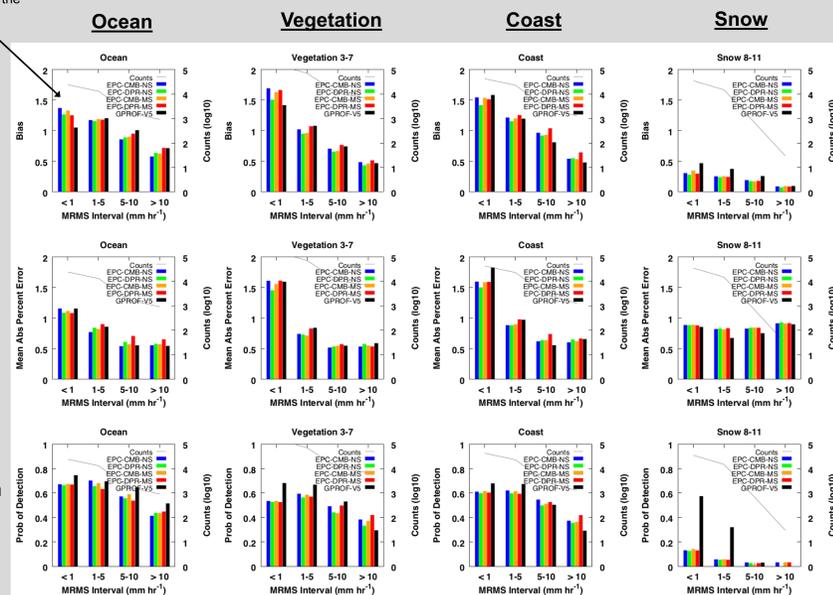
Bar colors indicate the scores from each of the EPC-based retrievals, shown in the scatterplots

Bias

Mean Absolute Percent Error (x 0.01)

Prob of Detection

EPC-Based Retrieval Skill Scores by Rain Interval (Relative to GMI-Matched MRMS) (same seven months between Nov 2015 and Sep 2016)



Nomenclature

EPC-CMB-NS: EPC-based estimate, where the combined (CMB) radar-radar algorithm (CORRA) Ku-band normal scan (NS) retrievals were weighted by distance in EPC space

EPC-DPR-NS: EPC-based estimate, where the radar-only (DPR) Ku-band normal scan (NS) retrievals were weighted by distance in EPC space

EPC-CMB-MS: EPC-based estimate, where the combined (CMB) radar-radar algorithm (CORRA) Ku+Ka-band matched scan (MS) retrievals were weighted by distance in EPC space

EPC-DPR-MS: EPC-based estimate, where the radar-only (DPR) Ku+Ka-band matched scan (MS) retrievals were weighted by distance in EPC space

For Version-4 processing, only EPC-CMB-NS and EPC-DPR-NS retrievals used

For Version-5 processing, EPC-CMB-MS and EPC-DPR-MS retrievals were added (four EPC-based estimates)